

LUNAR ROVER

The project aims to develop a 6 wheel Lunar Rover for conducting experiments in kinematic control and vision based navigation on lunar like terrain.

The project involves design, kinematics, and vision based path generation and multi-motor coordination. Both undergraduate and post-graduate students are involved in different aspects of the project. The details of each of the sub areas are as given under.

For more Details: <http://www.iitk.ac.in/dord/lunar-rover>